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Topical Review

Packing in protein cores

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Abstract

Proteins are biological polymers that underlie all cellular functions. The first high-resolution protein structures were determined by x-ray crystallography in the 1960s. Since then, there has been continued interest in understanding and predicting protein structure and stability. It is well-established that a large contribution to protein stability originates from the sequestration from solvent of hydrophobic residues in the protein core. How are such hydrophobic residues arranged in the core; how can one best model the packing of these residues, and are residues loosely packed with multiple allowed side chain conformations or densely packed with a single allowed side chain conformation? Here we show that to properly model the packing of residues in protein cores it is essential that amino acids are represented by appropriately calibrated atom sizes, and that hydrogen atoms are explicitly included. We show that protein cores possess a packing fraction of $\phi \approx 0.56$, which is significantly less than the typically quoted value of 0.74 obtained using the extended atom representation. We also compare the results for the packing of amino acids in protein cores to results obtained for jammed packings from discrete element simulations of spheres, elongated particles, and composite particles with bumpy surfaces. We show that amino acids in protein cores pack as densely as disordered jammed packings of particles with similar values for the aspect ratio and bumpiness as found for amino acids. Knowing the structural properties of protein cores is of both fundamental and practical importance. Practically, it enables the assessment of changes in the structure and stability of proteins arising from amino acid mutations (such as those identified as a result of the massive human genome sequencing efforts) and the design of new folded, stable proteins and protein-protein interactions with tunable specificity and affinity.

Keywords: proteins, random close packing, jamming

(Some figures may appear in colour only in the online journal)

1. Introduction

Proteins are biological polymers that play important roles in cellular processes ranging from the purely structural to the actively catalytic. Proteins are linear chains of different combinations of the 20 naturally occurring amino acid residues with variable chain lengths from tens to tens of thousands. A key feature that distinguishes proteins from other polymers is that each folds into a unique three-dimensional structure. Proteins typically fold spontaneously in aqueous solution at room temperature. The amino acid sequence is the only information required to specify a protein's unique structure [1, 2].

The amino acids can be grouped into two main categories: hydrophobic and hydrophilic. Hydrophobic residues form the solvent-inaccessible core of a protein and hydrophilic residues, both polar and charged, are on the solvent-accessible surface. As of 2017, the structures of more than 125 000 proteins have been determined, primarily by x-ray crystallography, with a median resolution of ≈ 2.5 Å and deposited in the protein data bank (PDB) [3]. This large database of atomic coordinates provides a wealth of structural information that can be used to analyze the physical properties of proteins and to understand how proteins interact and carry out their functions [4–14].

Each amino acid is made up of the same backbone unit of four heavy (non-hydrogen) atoms, N–C $_{\alpha}$ –C–O, and different combinations of side chain atoms that branch from the C_{α} atom (figure 1). The repeating units are joined by a peptide bond between the carboxyl carbon (C) of a given amino acid and the nitrogen (N) of the next. All interatomic bond lengths and bond angles are specified by the same basic stereochemistry that defines the structures of small molecules [15, 16]. The three-dimensional structure that a protein adopts is specified by the amino acid dihedral angles. For each amino acid in the protein chain, there are two backbone dihedral angle degrees of freedom, ϕ and ψ , and N_s side chain dihedral angle degrees of freedom, $\chi_1, ..., \chi_{N_s}$ (See figure 1 and appendix A.1.). N_s ranges from zero (for alanine and glycine) to five (for arginine). The third backbone dihedral angle is typically constrained to be $\omega = 180^{\circ}$ or 0° . Repetition of certain backbone ϕ and ψ values in a stretch of amino acids gives rise to specific secondary structures, such as α -helices and β -sheets [17, 18]. All proteins are formed from different combinations of α -helix, β -sheet, and 'random coil' structures. The interface between different elements of secondary structure are stabilized by interactions between the side chains [19–21]. In addition, side chain interactions on the surfaces of proteins also specify how different proteins bind to each other and to other molecules [6].

A physical model for an amino acid is a collection of overlapping spherical atoms with bond length and angle constraints as shown in figure 2. As is clear from figure 2, amino acids are non-spherical objects with complex shapes. Thus, in this representation, we can imagine proteins as interconnected non-spherical objects (with both backbone and side chain dihedral angle degrees of freedom) that form compact three-dimensional structures. This model is very different from coarse grained models, such as the C_{α} model, where proteins



Figure 1. Stick representation of a valine (Val) residue with each atom shown in a different color: C (green), N (blue), O (red), and H (white). The heavy (non-hydrogen) atoms are also labeled. The two backbone dihedral angles ϕ and ψ and one side chain dihedral angle χ_1 (defined by the atoms N–C_{α}–C_{β}–C_{γ 1}) are indicated.



Figure 2. (left) Illustration of a Val residue with each atom represented as a sphere: C (green), O (red), N (blue), and H (grey). The atom sizes are given in the first row of table 1. (right) All-atom representations of Val and Ile residues with connected backbones taken from PDB 1K5C. In both panels, the heavy atoms are labeled.

are represented by a chain of spherical beads (amino acids) [22], or the tube model, where the protein backbone is modeled as a flexible tube [23]. While these coarse-grained models can provide key insights into protein folding, they cannot be used to investigate the side chain conformations of residues in protein cores.

Many prior studies have argued that the cores of folded proteins are tightly packed. For example, several studies have measured the ratio between the volume of a core amino acid and its Voronoi volume to be greater than 70%, which suggests dense crystalline packing [24, 25]. In addition, experimental studies find that mutations in protein cores from small to large residues typically destabilize the protein, suggesting that there is very little empty space present to accommodate additional atoms [26, 27]. Studies have shown that the side chains within a protein core adopt a single set of conformations, i.e. the core is 'tightly packed', nearly jammed, and not a set of non-interacting solvent-excluded side chains. Indeed,

Table 1. Atomic radii used in the hard-sphere model and four other studies (one using explicit hydrogens [36] and three others using the extended atom model [24, 25, 37, 38]). Pauling [38] lists carbon radii using an extended atom model and specifies the radius for hydrogen. All radii are given in angstroms (Å).

Atom	C_{sp^3}	Caromatic	C _O	N	0	S	Н
This work	1.5	1.5	1.3	1.3	1.4	1.75	1.1
Word 1999 [36]	1.65	1.65	1.65	1.55	1.4	1.8	1.17
Richards 1974 [24]	2.0	1.7	1.7	1.7	1.4-1.6	1.8	N/A
Tsai 1999 [25, 37]	1.88	1.61-1.76	1.61-1.76	1.64	1.42-1.46	1.77	N/A
Pauling 1960 [38]	2.0	1.70	2.0	1.5	1.40	1.85	1.20

the more than 125000 protein structures in the Protein Data Bank show few alternate conformations for the side chains of core residues.

In this review, we summarize prior work on the structural properties of protein cores and provide strong evidence that although protein cores are densely packed, they are not as densely packed as crystalline solids. Instead, protein cores possess packing fractions $\phi \sim 0.56$ [14]. Even though this value is lower than that for crystalline solids (e.g. 0.74 for face-centered-cubic crystals), protein cores are solid-like with very little free volume that would allow side chain motion. We also show that static packings of 'bumpy' particles with complex, non-spherical shapes possess packing fractions below 0.6, yet still display solid-like properties and that the amino acids in protein cores can be modeled as random, densely packed non-spherical objects. The comparison of protein cores to packings of 'bumpy' particles explains why densely packed protein cores possess packing fractions near $\phi \approx 0.56$, rather than higher values closer to random close packing (0.64) or crystal close packing (0.74) for monodisperse spheres. We then relate our computational studies of dense packing in protein cores to experimental studies of mutations that are able to alter the structure and stability of proteins.

2. Packing efficiency in protein cores

By determining the packing fraction of protein cores one can begin to understand their structural and mechanical properties. For example, the shear modulus (i.e. the material response to applied shear stress) in jammed systems typically increases monotonically with the packing fraction since the number of stress-bearing interatomic contacts increases with the packing fraction [28]. Thus, the rigidity of protein cores is likely strongly correlated with the packing density [29, 30]. In addition, knowing the packing density is vital for predicting changes in stability from mutations to protein cores, many of which are disease-associated [31]. Accurate calculations of the packing density are also necessary to predict structure from sequence and to design new stable proteins [10, 32, 33].

One of the first studies of the packing density of protein cores was performed by Richards in 1974. At this time, only a few protein crystal structures were available. Richards focused on two proteins: lysozyme and ribonuclease S [24]. When a protein structure is obtained from x-ray crystallography, the resolution of the structure typically does not allow for the placement of the hydrogen atoms in the protein. In the past, researchers circumvented this problem by implementing an 'extended atom' model, where the atomic radii of each heavy atom are increased by a factor that depends on the number of hydrogen atoms that are bound to it [24, 25, 37]. New computational techniques allow for the accurate placement of hydrogen atoms in a protein crystal structure [36, 39], which provides a more detailed 'explicit hydrogen' model of proteins. Since hydrogen atoms comprise ~50% of all atoms in a protein, the extended atom approximation can strongly influence the accuracy of the structural model of the protein.

To accurately assess the packing fraction of proteins, one must calibrate and select proper atomic radii. In our recent work [14], we have chosen atomic radii that when used in a hard-sphere model of a dipeptide mimetic can reproduce the observed side chain dihedral angle distributions of non-polar amino acids in a database of high resolution crystal structures [14, 34, 35, 40, 41]. The values for the seven atomic radii are *C*_{sp³}, *C*_{aromatic}: 1.5 Å; *C*₀: 1.3 Å; *O*: 1.4 Å; *N*: 1.3 Å; *H*: 1.10 Å; and S: 1.75 Å. The atomic radii are similar to values of van der Waals radii reported in other studies, and typically smaller than those used in extended atom models [18, 24, 37, 38, 40, 42–49] (See table 1.). In figure 3, we show that the side chain dihedral angle distributions predicted using the hard-sphere model for Val and Ile dipeptides agree with the observed side chain dihedral angle distributions from high-resolution protein crystal structures (See appendix A.1 for the definitions of the side chain dihedral angles for core amino acids.). We have shown similar agreement between the observed and predicted side chain dihedral angle distributions for Cys, Leu, Met, Phe, Thr, Trp, Tyr, and Ser [41].

The packing fraction of each residue in a protein core can be calculated using

$$\phi_r = \frac{\sum_i \mathbf{V}_i}{\sum_i \mathbf{V}_i^{\nu}},\tag{1}$$

where V_i is the 'non-overlapping' volume of atom *i*, V_i^{ν} is the Voronoi volume surrounding atom *i*, and the summations are over all atoms of a particular residue. We also calculate the packing fraction of a protein core, ϕ_c , where both summations are over all atoms of all residues in a particular protein core. Voronoi cells were obtained for each atom using Laguerre tessellation, where the placement of the Voronoi faces are based on the relative radii of neighboring atoms (which is the same as the location of the plane that separates overlapping atoms) [14, 50] (See figure 4 for a representative Voronoi cell for a C_{α} atom in a protein core.). V_i was calculated by splitting overlapping atoms by the plane of intersection between the two atoms.



Figure 3. (left) The observed side chain dihedral angle probability distribution (black dotted line), $P(\chi_1)$, for Val residues in a database of high resolution protein crystal structures (described in [14, 34, 35]) compared to $P(\chi_1)$ predicted by the hard-sphere dipeptide mimetic model for Val using the explicit hydrogen atom representation (blue solid line). (center) The observed side chain dihedral angle probability distribution $P(\chi_1, \chi_2)$ for Ile. (right) The predicted side chain dihedral angle distribution for Ile using the hard-sphere dipeptide mimetic model. The probabilities increase from light to dark. The percentages give the fractional probabilities that occur in each of the three and nine rotamer bins in the left panel and center/right panels, respectively. The center and right panels are reprinted with permission from Gaines *et al* [14]. Copyright (2016) by the American Physical Society.

Average values for V_i and V_i^{ν} for the 11 residues that occur most frequently in protein cores are shown in appendix A.2.

Our analysis focuses on residues in protein cores. We have identified all core residues in a database of high resolution crystal structures (described in [14, 34, 35]) using a method described previously [14, 51]. In brief, non-core atoms are identified as those that are on the surface of the protein or near an interior void with a radius ≥ 1.4 Å. In this strict definition, a core residue is defined as any residue containing exclusively core atoms (including hydrogen atoms). This method identifies atoms adjacent to voids in the protein and removes them from the calculation of the packing fraction. According to this definition and using the explicit hydrogen representation, the proteins we considered have an average of 15 core residues of which 80% are Ala, Cys, Gly, Ile, Leu, Met, Phe, and Val.

As shown in figure 5, the average packing fraction of protein cores using the Voronoi method is $\phi_c \approx 0.56$ [14]. This value is for residues that only contain core atoms. The peak in the distribution of packing fractions for residues with (solvent-exposed) edge atoms decreases away from 0.56 as more edge atoms are included and more of the space surrounding the protein is considered in the calculation of ϕ_c (See appendix A.3.). For core residues, the value of 0.56 is much closer to packing fractions obtained for jammed packings of frictional or elongated particles rather than $\phi_c = 0.71$ –0.74 for packings with significant FCC crystalline order as proposed in earlier studies [24, 25, 37, 44, 46] (See section 4).

Many of these earlier studies that focused on the packing fraction in protein cores implemented the extended atom model with heavy atoms whose size increases with the number of bound hydrogens. In contrast, we implement an explicit hydrogen model. A comparison of the atom sizes in table 1 shows that prior studies selected values for the sp^3 and carbonyl carbons, nitrogen, and oxygen that are much larger than those in the explicit hydrogen model. Equally importantly, previous work did not calibrate their atom sizes to the side chain dihedral angle distributions observed in protein crystal structures. In figure 5(c), we show that the use of the extended



Figure 4. Image of a Voronoi cell of a C_{α} atom in a protein core. The red faces of the Voronoi cell surround the C_{α} atom, and are placed perpendicular to and at the midpoint between the dashed lines connecting the centers of overlapping atoms. The adjacent neighboring atoms are transparent and the remainder of the atoms are shown in ball and stick representation.

atom model (with atom sizes in row 3 of table 1) yields a side chain dihedral angle distribution for Ile that is significantly different than the observed distribution in figure 3(b).

To check the sensitivity of the results for the packing fraction, we also calculated the packing fraction of protein cores without using Voronoi tessellation. Instead, we placed small cubes with edge length l < 1 Å in random locations and orientations in the protein core and calculated the fraction of the cube that is occupied by protein atoms. Cubes are rejected if they overlap with solvent exposed residues. The average packing fraction of a protein core is obtained by averaging over a large number of cube placements. As shown in figure A1, we find similar results for the packing fraction using the random cube sampling method, which shows that the packing fraction of residues in protein cores is not sensitive to the method employed to calculate it.

To assess the effect of backbone connectivity on the packing efficiency in protein cores, we performed discrete element



Figure 5. (a) A comparison of the packing fraction ϕ_c of protein cores as a function of the number of core residues (N_R) using the explicit hydrogen (blue circles) and extended atom (red squares) representations. More residues are designated as core using the extend atom model (25 on average) than using the explicit hydrogen model (15 on average). The dashed and solid horizontal lines indicate the average packing fraction of each system, $\phi_c = 0.71$ for the extended atom and $\phi_c = 0.56$ for the explicit hydrogen models. (b) The probability distribution (red dotted line) of packing fractions at jamming onset $P(\phi)$ from simulations of mixtures of individual residues found in protein cores. The results were obtained by simulating 100 jammed packings of $N_R = 24$ residues with amino acid frequencies that match those in protein cores. The probability distribution of packing fractions of protein cores is shown by the solid black line. (c) The side chain dihedral angle probability distribution $P(\chi_1, \chi_2)$ for Ile predicted by the hard-sphere dipeptide model using the extended atom representation. Panels (a)–(c) are reprinted with permission from Gaines *et al* [14]. Copyright (2016) by the American Physical Society.

simulations to compress amino acid monomers into static (i.e. force and torque-balanced) jammed packings (See appendix A.5 for a detailed description of the packing-generation protocol.). We initialized the system by randomly inserting N_R residues into a cubic box (with periodic boundary conditions). We assumed that the residues, which are composed of rigidly connected, overlapping spherical atoms of different sizes (given in the first row of table 1), interact via purely repulsive linear spring forces. We then compress the system by small packing fraction increments $\Delta \phi$, followed by energy minimization. For sufficiently small $\Delta \phi$, the form of the purely repulsive potential does not influence the structure of the final packings. For jammed packings, the total potential energy per residue satisfies $U/N_R > 0$ following energy minimization. In contrast, unjammed packings will possess $U/N_R = 0$ after energy minimization. In this case, atomic motions can occur in the system without a concomitant increase in the total potential energy. Thus, we can identify the packing fraction at jamming onset ϕ_I as the one at which the minimized total potential increases above a small, nonzero threshold [52].

We studied mixtures of N_R residues with the fractions of Ala, Ile, Leu, Met, Phe, and Val residues matching the percentages found in protein cores. (We focused on non-polar residues, but because Gly has no side chain and Cys can form disulfide bonds, these were not included in the simulations.) These simulations generate disordered jammed packings with $\phi = 0.56$ similar to that found in protein cores (figure 5(b)). These results indicate that the connectivity of the protein backbone does not impose significant constraints on the free volume in protein cores.

To further analyze the packing efficiency in protein cores, we also calculated the distribution of the local packing fractions (i.e. ϕ for each residue type) in protein cores for both protein crystal structures and simulations. We find that the distributions of the local packing fractions for each residue type have similar average values, differing by <5%. In addition, the average values for the local packing fractions are similar to the global average in the core with standard deviations that are slightly larger, which reflects the fact that the local

packing fraction is obtained by averaging over fewer atoms than the global packing fraction. We also find that the average packing fraction of each amino acid type is similar to the average packing fraction in protein cores, except for Ala, which does not have a side chain dihedral angle degree of freedom. The similarity of the average packing fraction for individual residues and the average packing fraction in protein cores suggests that there are only small variations of the packing fraction within each protein core.

We also investigated the packing efficiency of proteinprotein interfaces. To do this, we compiled a protein-interface database of 123 crystal structures containing protein-protein and protein-peptide binding pairs. The structures are composed of both homo- and heterodimers with resolution ≤ 1.5 Å and less than 50% sequence identity. A core-interface residue is defined as any residue that is a surface residue in the individual protein monomers, but is completely buried after binding. Several studies have shown that the properties of protein-protein interfaces are similar to those of protein cores [8, 53]. Our analyses of protein cores and interfaces confirm this by showing that they possess a similar distribution of amino acids (i.e. primarily hydrophobic residues with few charged and polar residues). We find that 73% and 68% of the residues in protein cores and interfaces, respectively, are hydrophobic with similar frequencies for each amino acid. In addition, both the distributions of packing fractions for core and interface residues are peaked near 0.56 as shown in figure 6. This result demonstrates that protein-protein interfaces are packed similarly to protein cores.

3. Protein core repacking

Computational protein core repacking allows investigation of the uniqueness of the side chain conformation of residues in protein cores. Unique side chain conformations for core residues would imply that protein cores are jammed with very little free volume for rearrangements of side chains. There are two categories of protein core repacking investigations: one



Figure 6. The distribution of packing fractions $P(\phi)$ for core (solid line) and interface (dotted line) residues from high-resolution protein crystal structures.

starts with all possible sequences and seeks to recover the wild type sequence [54, 55] and the other starts with the wild type sequence and seeks to recover the observed combination of side chain dihedral angles and determine if alternative combinations are possible. Here we focus on the second, where the side chains of core residues are removed simultaneously and all side chain dihedral angle combinations of the starting sequence are sampled. The energy of each conformation is evaluated, the optimal conformation is predicted, and then compared to the observed structure.

To study repacking of protein cores, we again use the allatom, hard-sphere plus stereochemistry model. The cores of 221 proteins in the Dunbrack Database [34, 35] were studied. As a way to model the system at non-zero temperature and to improve the statistics, variations in bond lengths and angles are implemented by replacing each side chain with different instances of the side chain taken from high-resolution protein crystal structures [4]. Core residues were identified using the method discussed in section 2. As described in previous work [14, 41], the hard-sphere model treats each atom i as a sphere that interacts pairwise with all other non-bonded atoms j via the purely repulsive Lennard-Jones potential:

$$U_{\text{RLJ}}(r_{ij}) = \frac{\epsilon}{72} \left[1 - \left(\frac{\sigma_{ij}}{r_{ij}}\right)^6 \right]^2 \Theta(\sigma_{ij} - r_{ij}), \quad (2)$$

where r_{ij} is the center-to-center separation between atoms *i* and *j*, $\sigma_{ij} = (\sigma_i + \sigma_j)/2$, $\sigma_i/2$ is the radius of atom *i*, $\Theta(\sigma_{ij} - r_{ij})$ is the Heaviside step function, and ϵ is the strength of the repulsive interactions. Values for the atomic radii are listed in table 1.

Predictions of the side chain conformations of single amino acids are obtained by rotating each of the side chain dihedral angles $\chi_1, \chi_2, ..., \chi_n$ (with a fixed backbone conformation [56]), and finding the lowest energy conformation of the residue, where the total potential energy $U(\chi_1, ..., \chi_n)$ includes both intra- and inter-residue steric repulsive interactions. We then calculate the Boltzmann weight of the lowest energy side chain conformation of the residue, $P_i(\chi_1, ..., \chi_n) \propto e^{-U(\chi_1, ..., \chi_n)/k_{\rm B}T}$, where the small temperature, $T/\epsilon = 10^{-2}$, approximates hardsphere-like interactions. We select 50 bond length and angle variants, and for each we find the lowest energy dihedral angle conformation and corresponding $P_i(\chi_1, ..., \chi_n)$ values. We average P_i over the variants to obtain $P_m(\chi_1, ..., \chi_n)$. We then compare the particular dihedral angle combination $\{\chi_1^{\text{HS}}, ..., \chi_n^{\text{HS}}\}$ associated with the highest value of P_m to the side chain of the crystal structure $\{\chi_1^{\text{xtal}}, ..., \chi_n^{\text{xtal}}\}$. To assess the accuracy of the hard-sphere model in predicting the side chain dihedral angles of residues in protein cores, we calculate

$$\Delta \chi = \sqrt{(\chi_1^{\text{xtal}} - \chi_1^{\text{HS}})^2 + \dots + (\chi_n^{\text{xtal}} - \chi_n^{\text{HS}})^2}.$$
 (3)

We then determine the fraction $F(\Delta \chi)$ of residues of each type with $\Delta \chi$ less than 10°, 20°, and 30°. A description of the calculations of the error bars for $F(\Delta \chi)$ is provided in the appendix A.4.

In figure 7 (left), we investigate the accuracy of the hardsphere model in predicting the side chain dihedral angles of single residues in protein cores. For each amino acid (Ile, Leu, Met, Phe, Ser, Thr, Trp, Tyr, and Val), we calculate the fraction of residues, $F(\Delta\chi)$, for which the predicted side chain dihedral angle conformation is within 10°, 20° and 30° of the crystal structure value. Consistent with our prior results, the hard-sphere model accurately predicts the side chain dihedral angle combinations of single residues in the context of the protein for Ile, Leu, Phe, Thr, Trp, Tyr, and Val (\geq 90% within 30°) [51]. This result emphasizes that the purely repulsive hard-sphere model can accurately predict the side chain dihedral angle combinations for nonpolar and uncharged amino acids.

We find that the hard-sphere model is unable to predict with high accuracy the observed side chain conformations for two residues that we studied: Ser and Met. Our results for Met are consistent with those found in Virrueta *et al* [57]. In this prior work, we found that local steric interactions were insufficient to predict the shape of the $P(\chi_3)$ distribution for Met. It was necessary to add attractive atomic interactions to the hard-sphere model to reproduce the observed $P(\chi_3)$. Here, using only repulsive interactions, we predict $\approx 80\%$ of Met residues are within 30° of the crystal structure. Our results for Ser (only 38% within 30°) are also consistent with our prior work in Caballero *et al* [51]. We speculate that because the side chain of Ser is small, hydrogen-bonding interactions must be included to correctly place its side chain. In contrast, we suggest that the more bulky Thr and Tyr side chains cause steric interactions to determine the positioning of their side chains, even though they are able to form hydrogen bonds [40].

In addition to single residue rotations, we performed core repacking using combined rotations of interacting core residues in each protein [58]. For the combined rotation method, all residues in an interacting cluster are rotated simultaneously (with fixed backbone conformations), and the global minimum energy conformation is identified. A cluster of interacting residues is defined such that side chain atoms of each



Figure 7. (left) Single and (right) combined residue rotations in the context of the protein core: The fraction ($F(\Delta \chi)$) of each residue type for which the hard-sphere model prediction of the side chain conformation deviates by $\Delta \chi < 10^{\circ}$ (yellow), 20° (red), or 30° (blue) from the crystal structure. This figure is reprinted with permission from Gaines *et al* [58]. Copyright (2017) by Oxford University Press.

residue in the cluster interact with one or more other residues in the cluster, but do not interact with the side chains of other core residues in the protein.

Single and combined rotations have the same prediction accuracy (figures 7 and 8), which shows that there are very few arrangements of the side chains in protein cores that are sterically allowed and that the side chain conformations of most core residues are dominated by packing constraints. Thus, even though protein cores possess packing fraction $\phi \approx 0.56$, this result implies that there are no alternative sterically allowed conformations of core residues other than those in the crystal structure. If alternative sterically allowed conformations existed, we would have found them using the collective repacking method and thus the prediction accuracy would have dramatically decreased relative to the value for single residue rotations. It does not. Thus, the results for collective repacking reveal that the structures of protein cores are uniquely specified by steric interactions. This conclusion is consistent with those reached by Word et al [36], where they found that 'in a wellpacked core region, it is rare that a bond angle can be rotated much in either direction without producing clashes'.

4. Jammed packings of spherical and nonspherical particles

A strict definition of jamming means that a disordered system is solid-like and possesses a static shear modulus [28]. However, jamming also implies that a system is confined to a small region of configuration space, such that little or no motion of the constituent particles can occur. The results presented in sections 2 and 3 provide several indications that residues in protein cores are jammed in this latter sense. First, for nearly all protein cores, single and collective repacking give the same side chain dihedral angle combinations found in the protein crystal structures. This result emphasizes that there are no alternative low energy side chain conformations for core residues. Second, the packing fraction of protein cores is $\phi \approx 0.56$, which is similar to those reported for disordered jammed packings of frictional [59] and elongated particles [60–62].



Figure 8. Comparison of the accuracy of single and combined rotations for core residues in 221 proteins [34, 35]. Each bar shows the fraction of residues, $F(\Delta \chi)$, for which the hard-sphere model prediction of the side chain conformation has $\Delta \chi < 30^{\circ}$ for single (blue) or combined (red) rotations. This figure is reprinted with permission from Gaines *et al* [58]. Copyright (2017) by Oxford University Press.

In this section, we present the results of simulations of jammed packings in three spatial dimensions (3D) for a wide variety of particle shapes including monodisperse spheres, polydisperse spheres, spheres with varying sizes of asperities (or 'bumps'), ellipsoids, ellipsoids with varying sizes of asperities, and non-axisymmetric, elongated particles. This range of shapes allows us to study the influence of the particle aspect ratio and surface bumpiness on the packing fraction and determine which particle shapes produce packing fractions that match the packing fraction of residues in protein cores (See the appendix A.5 for a detailed description of the computational methods used to generate static packings of spherical and nonspherical particles.).

We start the discussion with jammed packings of monodisperse spheres. In monodisperse systems, the packing fraction depends on the degree of order that is present in the system. For example, in figure 9, we show that the packing fraction varies with the global bond orientational order parameter Q_6 [63, 64], which measures the degree to which the separation vectors connecting a given particle and its nearest neighbors



Figure 9. Global bond orientational order parameter Q_6 versus packing fraction ϕ for 100 jammed packings of monodisperse spheres.

are consistent with icosahedral symmetry. $Q_6 \approx 0.57$ for perfect FCC crystalline sphere packings with $\phi \approx 0.74$. The packing fraction for jammed packings of monodisperse spheres decreases as Q_6 decreases, reaching random close packing $\phi \approx 0.64$ in the limit $Q_6 \rightarrow 0$ [65]. Jammed packings with different values of Q_6 can be obtained by varying the rate at which kinetic energy is drained from the system [66]. For the present studies, we consider the limit of fast quenching rates, which gives rise to disordered packings.

Particle size differences can strongly decrease a system's tendency to order. In previous studies, we focused on jammed packings of bidisperse spheres with half large spheres, half small spheres, and a modest diameter ratio of d = 1.4 [52, 67]. It is difficult to generate ordered packings of such bidisperse spheres using the packing-generation methods employed here. However, large size ratios ($d \ge 2.4$) can also increase the packing fraction of jammed packings of polydisperse spheres. In this case, small spheres can fill in the gaps between contacting larger spheres. For example, Apollonian sphere packings [68] characterized by a continuous distribution of particle sizes possess packing fractions that approach 1.

In the all-atom hard-sphere model of proteins, we consider seven atom types with differing diameters. The largest diameter ratio is d = 1.8 between sulfur (which is rare) and hydrogen atoms; the next largest diameter ratio (d = 1.5) is between sp³ carbon and hydrogen atoms. Thus, we expect that jammed sphere packings composed of mixtures of atoms with the same sizes and number fractions as in protein cores will have packing fraction $\phi \approx 0.64$. This result was shown previously in [14]. Thus, jammed packings composed of individual spheres with polydispersity that matches atom size differences in protein cores possess packing fractions that are larger than the values we observe in protein cores (section 2).

We now consider jammed packings of symmetric elongated particles, i.e. spherocylinders and ellipsoids, as a function of the aspect ratio α . In figure 10, we show that the packing fraction $\phi(\alpha)$ is qualitatively the same for jammed packings of spherocylinders and ellipsoids. $\phi \approx 0.64$ for spherical particles with $\alpha = 1$, increases for $\alpha > 1$, reaches a peak near $\alpha \approx 1.5$ with $\phi > 0.7$, and then decreases to a plateau value of $\phi \approx 0.68$ at large α .



Figure 10. Jammed packing fraction ϕ versus aspect ratio α for frictional spheres (blue asterisks) from [59], bumpy (green triangles) composite spheres, smooth, prolate ellipsoids of revolution from [61] (dotted line) and [62] (solid line) and spherocylinders (dashed line) from [60]. The static friction coefficient for the frictional spheres varies from $\mu = 10^{-4}$ to 10 from top to bottom. For the bumpy composite spheres (figures 11(a)and (b)), twelve bumps are placed on the vertices of an icosahedron, and the relative sizes of the bumps are decreased to increase the bumpiness B from $\approx 10^{-2}$ to 0.15 from top to bottom. We also show the packing fraction and aspect ratio for Ala (open diamond), Ile (open leftward triangle), Leu (open circle), Met (open square), Phe (x), and Val (open upward triangle) residues in protein cores. The error bars indicate the root-mean-square fluctuations from averaging over instances of each residue with different backbone and side chain conformations. Results for bumpy ellipsoids are indicated by the filled rightward and upward triangles and results for the nonaxisymmetric shapes in figures 11(g) and (h) are indicated by the filled diamond and circle, respectively.

To compare the results for jammed packings of symmetric, elongated particles to packings of amino acids presented in section 2, we define a generalized aspect ratio and surface bumpiness to characterize the shape of composite particles made from collections of overlapping spheres. We define bumpiness by

$$B = \sqrt{\int \mathrm{d}\hat{u} \frac{\left(\vec{R}(\hat{u}) - \vec{R}(\hat{u})\right)^2}{\mathcal{R}^2(\hat{u})}},$$
(4)

where \hat{u} is a unit vector with an origin at the geometric center of the composite particle, the integral is over all orientations of \hat{u} , $\vec{R}(\hat{u})$ gives the location on the surface of the composite particle along \hat{u} , and $\vec{\mathcal{R}}(\hat{u})$ gives the location on the surface of a reference prolate ellipsoid of revolution along \hat{u} . The bumpiness *B* for a given composite particle will depend on the orientation of the reference prolate ellipsoid axis \hat{e} and the values of the major *a* and minor *b* axes. The calculations of bumpiness will allow us to identify particle shapes with the same surface roughness as amino acids.

To define the aspect ratio α for composite particles, we find the reference prolate ellipsoid of revolution that yields the smallest bumpiness. We first fix the reference ellipsoid axis \hat{e} to be in the direction that gives the largest distance between the geometric center and the surface of the composite particle. We then minimize $B(\hat{e}, a, b)$ over a and b at fixed \hat{e} , and define



Figure 11. Examples of the composite particle shapes investigated in the packing simulations: bumpy spheres with (a) B = 0.008, $\alpha = 1.00$ and (b) B = 0.113, $\alpha = 1.00$; bumpy ellipsoids with (c) B = 0.015, $\alpha = 1.40$ and (e) B = 0.162, $\alpha = 1.40$; (e) Ala and (f) Phe residues; and ((g) and (h)) two examples of non-axisymmetric composite particles.

 $\alpha = a/b$ for the optimal values of the major and minor axes of the reference ellipsoid.

Figure 10 shows the packing fraction versus aspect ratio for Ala, Val, Ile, Leu, Met, and Phe residues in protein cores. As discussed in section 2, most core residues have packing fractions near 0.55–0.56. The aspect ratios of amino acids depend on the amino acid type and their backbone and side chain conformations. The average aspect ratios vary from $\alpha \approx 1.4$ for Val to ≈ 2.3 for Phe. The error bars in both ϕ and α are obtained from the root-mean-square fluctuations over different instances (i.e. varying backbone and side chain dihedral angle conformations) of each residue in protein cores.

The packing fraction $\phi \approx 0.55$ –0.56 observed for amino acids in protein cores with nominal aspect ratios in the range $1.4 \leq \alpha \leq 2.3$ is not consistent with the packing fraction $\phi \approx 0.7$ obtained for jammed packings of smooth ellipsoids and spherocylinders with aspects ratios in the same range. Thus, elongated, smooth, axisymmetric particles are not sufficient to model packings of amino acids in protein cores.

A method for decreasing the packing efficiency of particle packings is to include frictional, tangential forces between particles or add asperities (or 'bumps') to the surface of the particles as shown in figures 11(a) and (b). In prior work, we showed in 2D that we could decrease the packing fraction of bidisperse disks from random close to random loose packing (corresponding to more than a 10% decrease in packing fraction) by increasing the bumpiness or effective friction coefficient between disks [69]. In figure 10, we include results from [59] showing that the packing fraction of frictional spheres (asterisks) in 3D decreases by a similar percentage from $\phi \approx 0.64$ to ≈ 0.55 as the static friction coefficient μ increases from 10^{-4} to 10. In the appendix A.5, we provide a description of the computational method used to generate frictional sphere packings.

We find similar results for bumpy spheres (green squares) in figure 10. Here, the bumpy spheres are composite particles



Figure 12. Surface bumpiness *B* versus aspect ratio α for several particle shapes considered in the packing simulations. For bumpy spheres (green squares) with $\alpha = 1$ created by placing spheres on the vertices of an icosahedron, bumpiness can be varied over the range $0 \leq B \leq 0.15$. For prolate ellipsoids (black dots) with 8 or 14 spherical bumps (black dots), we can achieve maximum bumpiness values $B \approx 0.17$ over a wide range of α indicated by the grey rectangle. We also show bumpiness versus aspect ratio for Ala (diamond), Ile (leftward triangle), Leu (circle), Met (square), Phe (x), and Val (upward triangle) residues in protein cores. *B* and α for the non-axisymmetric particles in figures 11(g) and (h) are given by the filled red diamond and magenta circle, respectively.

made from twelve spheres arranged on the vertices of an icosahedron. We decrease the ratio *r* of the size of each sphere to the size of the icosahedron to increase the bumpiness *B*. We show in figure 12 that for bumpy spheres formed from an icosahedron, we can generate $0 \leq B \leq 0.15$ (corresponding to $5 \geq r \geq 0.63$), which accounts for the decrease in packing fraction of the green squares in figure 10 from top to bottom.

As discussed above, amino acids cannot be modeled using spherical shapes with $\alpha \approx 1$ or using elongated, smooth particles. Thus, we performed studies of bumpy ellipsoids with $\alpha > 1$ to model packings of amino acids in protein cores. For

bumpy ellipsoids, we place spheres on the surface of a reference prolate ellipsoid with specified major and minor axes. Two spheres were placed on the ends of the reference ellipsoid and either 3 or 4 spheres were placed at equal angular intervals on the ellipsoid surface at distances along the long axis that divide the long axis into 3 or 4 equal segments. Thus, the bumpy ellipsoids we studied were made up of either 8 or 14 spheres as shown in figures 11(c) and (d). In figure 12, we show that we can study bumpiness values $B \leq 0.17$ over a wide range of aspect ratios using this method for constructing bumpy axisymmetric elongated particles.

In figure 10, we show the packing fraction for jammed packings of bumpy ellipsoids over a range of bumpiness values for two aspect ratios, $\alpha \approx 1.4$ and 2.25, which spans the range of aspect ratios calculated for amino acids in protein cores. For both aspect ratios, the packing fraction decreases from the values obtained from packings of smooth elongated particles to $\phi \approx 0.55$ as the bumpiness is increased from B = 0.01 to 0.17.

An interesting point to note, as shown in figure 12, is that amino acids found in protein cores (e.g. Ala and Phe in figures 11(e) and (f)) possess bumpiness values between B = 0.25 and 0.3, whereas bumpy axisymmetric shapes have $B \lesssim 0.17$. Thus, we also studied jammed packings of the nonaxisymmetric composite particles pictured in figures 11(g)and (h). Five spheres make up the composite particle pictured in panel (g). Three are arranged in a straight line, and the other two spheres are placed in a plane perpendicular to the long axis of the composite particle and at an angular separation of 90°. The composite particle in panel (h) contains 7 spheres with two spheres each placed at the top and bottom of the particle in planes perpendicular to the long axis and in staggered orientations. The bumpiness and aspect ratio of these non-axisymmetric composite particles is varied by changing the size of the bumps compared to the size of the sphere that circumscribes the composite particle. For these two types of non-axisymmetric particles, we were able to increase the maximum bumpiness to $B \approx 0.4$, which is even larger than that of any of the core amino acids (figure 12).

As shown in figure 10, the packing fractions for jammed packings of the non-axisymmetric particles in figures 11(g) and (h) (with B = 0.33 and 0.39) are $\phi \approx 0.56$. These results show that jammed packings of particles with the same B and α as those found for amino acids yield the same packing fraction as amino acids in protein cores. Thus, for the purpose of understanding the packing fraction in protein cores, it is helpful to picture amino acids as bumpy, elongated, and non-axisymmetric objects with a given surface bumpiness and aspect ratio.

5. Mutations in protein cores

Additional insight into the packing efficiency in protein cores can be obtained by examining the results from experimental studies of protein core mutations. Several groups have experimentally investigated the potential plasticity of protein cores by performing mutations, i.e. by changing the identities core amino acids. Lim and Sauer simultaneously mutated several hydrophobic residues in the core of a small protein, and used a genetic screen to identify those that were functional and stable. They found that very few combinations of amino acids other than the wildtype set resulted in a stable, folded protein [26]. The functional new cores were dominated by hydrophobic amino acids and the total side chain volumes were within 10% of the original core volume. Combinations of residues outside of these requirements were nonfunctional. Moreover, stereochemical constraints further restricted the allowed sequence space. For example, although many permutations of core residues can maintain the same total volume and hydrophobicity in the core, they do not result in a protein with the same structure and stability [26]. As a result of hydrophobic, volume, and steric constraints, only 0.3% of 60 000 sequences sampled are fully functional [26, 27]. These observations provide experimental support for the dominance of steric interactions in protein cores. Similar experimental results have been found in other proteins [70–73].

Liu et al investigated how mutations from small to large residues in the core affect protein stability [74]. This work illustrates the difficulty in generalizing the effects of a particular type of mutation at different locations and in different proteins. In this work, three Ala residues in the core of a small protein were mutated, individually, to either Cys, Ile, Leu, Met, Phe, Trp, or Val, and the resulting effect on protein stability was determined. They also solved the crystal structures of several of the mutated proteins. They found that in all cases, to varying degrees, to accommodate the larger amino acid side chain, the backbone moved. Interestingly, at two of the three positions, even with backbone movement, the protein with a larger side-chain was destabilized relative to the protein with the original Ala. However, at one position, even large increases in volume (Ala to Phe or Trp) could be accommodated by backbone movement to give a mutated protein with similar stability to that of the parent protein. Liu et al hypothesized that this behavior was due to a cavity in the protein near the mutation site, which allowed for more flexibility in this region of the protein [74] (See also section 6.).

This work shows that the protein core is not able to accommodate mutations to larger residues without significant rearrangement and subsequent destabilization of the original structure. If substantial empty space existed in the protein core, then mutations of this type would likely have small effects because they would fill the existing empty space and not require backbone rearrangements. Instead, backbone rearrangements are necessary to accommodate larger amino acids, supporting the idea that protein cores are tightly packed [74]. This example also illustrates that much is still unknown about protein core packing and how it controls protein stability. The current state of knowledge is such that one can predict neither the backbone movements in response to the incorporation of a larger side chain, nor the changes in stability that result from these structural changes.

6. Conclusions and future directions

The computational studies described in this Review have established that protein cores are comprised of irregularly shaped objects that are packed into disordered jammed arrangements with $\phi \approx 0.56$ [14]. For a given core, there are no alternative arrangements of the same amino acids that are consistent with a well-packed core with no atomic overlaps [51, 58]. It has also been shown, both experimentally and computationally, that there are a small number of combinations of different core residues that can properly fit in and fill a given core, and thus give rise to a stable folded protein [26, 27, 74-76]. There are also experimental examples in which amino acids in the core are substituted with ones that are either smaller or larger. Often such substitutions result in changes in the backbone positions. With the current state of understanding in the field, it is not possible to reliably predict such movements. For some mutations, the rearranged protein is as stable as the starting protein, for others it is less stable. Again, the state of the art in computational modeling is such that it is not possible to predict either the structure or the stability of the repacked, rearranged protein [77].

Even dense packing of amino acids in protein cores results in some void space not occupied by amino acids. There has been some analysis of voids in proteins using a range of probe sizes [25, 78]. Various probe sizes are used to identify void connectivity in the protein and to remove small physically irrelevant voids. Obviously, an exceedingly small probe (e.g. radius ≤ 0.05 Å) will identify a large amount of void space, because even the very smallest voids will be counted. Conversely, a large probe (e.g. radius $\gtrsim 1.4$ Å) will identify few, if any, voids. A 'reasonable' probe size to use seems to be around 0.5 Å. Using such a probe size, Cuff et al examined void statistics in a dataset of high-resolution protein structures [78]. They found that the median total void volume was $\approx 15 \text{ Å}^3$ per residue. To put this into perspective. a CH_2 group and a water molecule have a volume of ${\approx}25$ Å³, which indicates that the voids in protein cores are small. In future studies, we will consider the location and size of buried voids to predict the consequences of changes of amino acid size and sequence in protein cores. Perhaps, there is a strong correlation between the location of voids and backbone movement in response to point mutations.

There have been a number of studies in the jamming literature (e.g. [28]) that have shown a strong connection between the packing fraction, number of interparticle contacts, and the mechanical response of jammed packings to an applied stress. The applied stress can be a pulling force, compression, or shear. In jammed systems, one can infer the linear mechanical response of a system simply by measuring the packing fraction (or number of interparticle contacts) without actually applying a stress. The connection between packing fraction, number of atomic contacts, and mechanical response has not yet been established for protein cores, but it is an interesting future direction of research. We advocate future studies of protein cores aimed at understanding to what extent they can be viewed as jammed systems with similar mechanical response to that for jammed particle-based packings.

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Appendix

In this appendix, we provide additional details that support the results presented in the main text.

A.1. Definition of side chain dihedral angles

Dihedral angles in proteins are specified by 4 consecutive heavy atoms along the protein chain. The side chain dihedral angles (and the atoms that define them) of amino acids in protein cores are given in table A1. Each side chain dihedral angle χ_x , where x = 1,2,3,4 is specified by

$$\cos(\chi_x) = \frac{(\vec{r}_{ij} \times \vec{r}_{jk}) \cdot (\vec{r}_{jk} \times \vec{r}_{kl})}{|\vec{r}_{ij} \times \vec{r}_{ik}| |\vec{r}_{ik} \times \vec{r}_{kl}|},\tag{A.1}$$

where *i*, *j*, *k*, and *l* are four consecutive heavy atoms along the side chain and \vec{r}_{ij} is the separation vector pointing from atom *j* to *i*.

A.2. Residue volumes

In table A2, we provide the volume of the 11 residues that occur most frequently in protein cores using the explicit hydrogen representation. Gly and Ala have the smallest volumes and Tyr and Trp have the largest. The average packing fraction for a given residue can be obtained by dividing the entry in column 1 by that in column 2. The atomic volumes for the explicit hydrogen model differ quantitatively from those obtained using the extended atom model. The Voronoi volumes are relatively insensitive to the choice of the atom sizes.

A.3. Packing fraction with edge atoms and calculated using random placement of cubes

In the main text, we focused on results for residues containing only core atoms and no edge atoms. We also studied the variation of the packing fraction with the distance from the core of the protein by plotting the packing fraction distribution $P(\phi)$ as a function of the number of solvent-exposed (edge) atoms per residue as shown in figure A1 (right). For the calculation of $P(\phi)$, we do not include residues that have atoms with Voronoi cells that are terminated by the faces of the bounding box. As the number of edge atoms per residue increases, the peak in the packing fraction decreases away from 0.56 and a pronounced tail at low ϕ develops as more of the space surrounding the protein is included in the calculation of the packing fraction. Above six edge atoms per residue, the peak in $P(\phi)$ near $\phi \approx 0.5$ disappears and the weight in $P(\phi)$ is mainly near zero.

We also calculated the packing fraction of protein cores using random sampling rather than using Voronoi tessellation. We placed cubes with edge length $\ell < 1$ Å in random locations



Figure A1. (left) The distribution of packing fractions $P(\phi)$ for protein cores calculated using the Voronoi method (black line) and the random sampling method with cube edge lengths of 0.1 (blue dashed line), 0.05 (red dotted line), 0.025 (yellow x), and 0.01 Å (purple circles). (right) The distribution of packing fractions $P(\phi)$ for residues that include 0, 2, 4, 6, and 8 solvent-exposed (edge) atoms. The data in both panels is obtained from high-resolution protein crystal structures.

Table A1. The groups of four heavy atoms that define the side chain dihedral angles for 9 of the 11 residues that occur most frequently in protein cores. The other two residues, Ala and Gly, do not possess side chain dihedral angle degrees of freedom.

Amino Acid	Side chain dihedral angle	Atoms	
Ile	χ_1	$N-C_{\alpha}-C_{\beta}-C_{\gamma 1}$	
	χ_2	C_{α} – C_{β} – $C_{\gamma 1}$ – C_{δ}	
Leu	χ_1	$N-C_{lpha}-C_{eta}-C_{\gamma}$	
	χ_2	C_{α} – C_{β} – C_{γ} – $C_{\delta 1}$	
Met	χ_1	$N-C_{\alpha}-C_{\beta}-C_{\gamma}$	
	χ_2	C_{lpha} – C_{eta} – C_{γ} – S_{δ}	
	χ_3	C_{eta} – C_{γ} – S_{δ} – C_{ϵ}	
Phe	χ_1	$N-C_{\alpha}-C_{\beta}-C_{\gamma}$	
	χ_2	C_{α} – C_{β} – C_{γ} – $C_{\delta 1}$	
Thr	χ_1	$N-C_{\alpha}-C_{\beta}-O_{\gamma}$	
Trp	χ_1	$N-C_{\alpha}-C_{\beta}-C_{\gamma}$	
	χ_2	C_{α} – C_{β} – C_{γ} – $C_{\delta 1}$	
Tyr	χ_1	$N-C_{\alpha}-C_{\beta}-C_{\gamma}$	
	χ_2	C_{α} – C_{β} – C_{γ} – $C_{\delta 1}$	
Ser	χ_1	$N-C_{lpha}-C_{eta}-O_{\gamma}$	
Val	χ_1	$N - C_{\alpha} - C_{\beta} - C_{\gamma 1}$	

Table A2. Atomic $(\sum_i V_i)$ and Voronoi $(\sum_i V_i^v)$ volumes for the 11 residues that occur most frequently in protein cores using the explicit hydrogen representation. The Voronoi volumes calculated in [79] are also included in the fourth column to illustrate that Voronoi volumes are relatively insensitive to the choice of atom sizes.

Residue	$\sum_{i} V_i (\text{\AA}^3)$	$\sum_{i} V_{i}^{\nu} (\text{\AA}^{3})$	$\sum_{i} V_{i}^{v} (\text{\AA}^{3}) [79]$
Ala	48.8	88.9	91.5
Cys	64.3	109.1	114.4
Gly	35.6	63.5	67.5
Ile	88.1	163.6	162.6
Leu	88.1	164.4	163.4
Met	92.7	165.2	165.9
Phe	100.7	186.4	198.8
Thr	69.0	122.3	126.0
Trp	121.9	220.9	237.2
Tyr	107.5	194.9	209.8
Val	75.0	139.5	138.4

hard-sphere model is less than $\Delta \chi$ from the observed side chain conformation that are shown in figures 7 and 8. To assess the accuracy of the hard-sphere model in predicting the side chain dihedral angle conformations of residues in protein cores, repacking calculations were performed using $N_{\nu} = 300$ bond length and angle variants for each core residue. For each residue, we randomly select *M* bond length and angle variants out of the N_{ν} variants. For each set of variants, we identified the optimal side chain dihedral angle combination and calculated $\Delta \chi$. We then repeat this process *N* times, which yields a set of $N\Delta \chi$ values. We then calculated the mean fraction of residues $F(\Delta \chi)$, which satisfy $\Delta \chi < 10^{\circ}$, 20° , or 30° , and the standard deviation. We used N = 50 and M = 50 for single residue rotations and N = 50 and M = 30for combined rotations.

A.5. Computational methods for generating static packings

To understand why amino acids pack at $\phi \approx 0.56$ in protein cores, we carried out packing simulations of individual elongated, bumpy, and frictional particles. First, we describe the methods for generating packings of elongated and bumpy particles. Each composite particle is made up of *n* spherical

the cube that is occupied by protein atoms. Cubes are rejected if they overlap with solvent-exposed residues. The average packing fraction of a protein core is obtained by averaging over a large number of cube placements. As shown in figure A1 (left), we find similar results for the packing fraction using the random sampling and Voronoi tessellation methods. In the limit $\ell \rightarrow 0$, the packing fraction converges and displays a peak near 0.56. With larger cubes, it is difficult to sample exclusively core atoms and the void spaces associated with them.

and orientations in the protein core and calculated the fraction of

A.4. Error bars for repacking studies

We next describe the calculation of the error bars for the fraction $F(\Delta \chi)$ of residues for which the prediction of the

asperities placed on the vertices of an icosahedron or locations on the surface of a prolate ellipsoid of revolution. Spherical asperities *i* and *j* on composite particles *C* and *C*' interact via the pairwise potential $U_{ij}^{CC'} = \frac{\epsilon}{2}(1 - r_{ij}/\sigma_{ij})^2\Theta(\sigma_{ij} - r_{ij})$, where ϵ is the energy scale of the interaction, r_{ij} is the distance between the centers of asperities *i* and *j*, $\sigma_{ij} = (\sigma_i + \sigma_j)/2$ is the average diameter of asperities *i* and *j*, and Θ is the Heaviside step function. Thus, composite particles *C* and *C*' interact via $U^{CC'} = \sum_{i,j} U_{ij}^{CC'}$. The total potential energy of the system is $U = \sum_{C>C'} U^{CC'}$.

Jammed packings are obtained by employing a compression protocol similar to that in [62]. We first place N composite particles randomly in a cubic periodic cell of unit volume. At each step we increase the asperity sizes σ_i and bond lengths δ_{ij} between asperities (fixing the ratios between σ_i and δ_{ii}) corresponding to $\Delta \phi \approx 10^{-3}$, and then we relax the system to the nearest potential energy minimum using dissipative dynamics, where the dissipative forces are proportional to the composite particle velocities. If the potential energy is zero after energy minimization (i.e. below a small threshold $U/N < 10^{-4}$), we continue compression. Otherwise, we decompress the system, and the compression increment $\Delta\phi$ is halved each time we switch from compression to decompression. We stop the packing-generation protocol when the potential energy is nonzero and the average particle overlaps are between 0.01% and 0.1%. We measure the final packing fraction at jamming onset, which is insensitive to the choice of $\Delta \phi$ and the overlap threshold, provided they are sufficiently small.

In the main text, we also described packings of frictional spheres [59] that interact via the Cundall–Strack model [80]. Cundall–Strack friction models microscopic frictional interactions through the use of linear tangential springs at intergrain contacts. The tangential (frictional) force is given by $F_{ij}^t = -K_t u_{ij}^t$, where K_t is the tangential spring stiffness (typically set to be roughly the same as the normal contact stiffness) and u_{ij}^t is the relative displacement of the point of contact between grains *i* and *j*. At each contact, the Coulomb sliding condition, $F_{ij}^t \leq \mu F_{ij}^r$, is enforced, where F_{ij}^r is the radial (normal) component of the force between particles *i* and *j* and μ is the static friction coefficient. When F_{ij}^t exceeds μF_{ij}^r , we set $u_{ij}^t = \mu F_{ij}^r/K_t$, and the grains slide relative to each other. The compression algorithm to generate jammed frictional sphere packings is the same as that used to generate jammed bumpy particle packings.

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